

Position & Source: Position vector \vec{r} , source vector \vec{r}' , separation vector $\vec{\Delta r} = \vec{r} - \vec{r}'$

Fundamental Theorems of Vector Calculus:

$$\int_{\vec{a}}^{\vec{b}} \nabla f \cdot \vec{dl} = f(\vec{b}) - f(\vec{a}) \quad \int \nabla \cdot \vec{A} \, d\tau = \oint \vec{A} \cdot \vec{da} \quad \int (\nabla \times \vec{A}) \cdot \vec{da} = \oint \vec{A} \cdot \vec{dl}$$

Cartesian Coordinates: $\vec{dl} = dx\hat{x} + dy\hat{y} + dz\hat{z} \quad d\tau = dx \, dy \, dz$

$$\nabla f = \frac{\partial f}{\partial x} \hat{x} + \frac{\partial f}{\partial y} \hat{y} + \frac{\partial f}{\partial z} \hat{z} \quad \nabla \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

$$\nabla \times \vec{A} = \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) \hat{x} + \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) \hat{y} + \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \hat{z} \quad \nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$

Spherical Coordinates: $x = r \sin\theta \cos\phi, y = r \sin\theta \sin\phi, z = r \cos\theta$

$$\vec{dl} = dr\hat{r} + r \, d\theta\hat{\theta} + r \sin\theta \, d\phi\hat{\phi} \quad d\tau = r^2 \sin\theta \, dr \, d\theta \, d\phi$$

$$\nabla f = \frac{\partial f}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{\theta} + \frac{1}{r \sin\theta} \frac{\partial f}{\partial \phi} \hat{\phi} \quad \nabla \cdot \vec{A} = \frac{1}{r^2} \frac{\partial(r^2 A_r)}{\partial r} + \frac{1}{r \sin\theta} \frac{\partial(\sin\theta A_\theta)}{\partial \theta} + \frac{1}{r \sin\theta} \frac{\partial A_\phi}{\partial \phi}$$

$$\nabla \times \vec{A} = \frac{1}{r \sin\theta} \left(\frac{\partial(\sin\theta A_\phi)}{\partial \theta} - \frac{\partial A_\theta}{\partial \phi} \right) \hat{r} + \frac{1}{r} \left(\frac{1}{\sin\theta} \frac{\partial A_r}{\partial \phi} - \frac{\partial(r A_\phi)}{\partial r} \right) \hat{\theta} + \frac{1}{r} \left(\frac{\partial(r A_\theta)}{\partial r} - \frac{\partial A_r}{\partial \theta} \right) \hat{\phi}$$

$$\nabla^2 f = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial f}{\partial r} \right) + \frac{1}{r^2 \sin\theta} \frac{\partial}{\partial \theta} \left(\sin\theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{r^2 \sin^2\theta} \frac{\partial^2 f}{\partial \phi^2}$$

Cylindrical Coordinates: $x = s \cos\phi, y = s \sin\phi, z = z$

$$\vec{dl} = ds\hat{s} + s \, d\phi\hat{\phi} + dz\hat{z} \quad d\tau = s \, ds \, d\phi \, dz$$

$$\nabla f = \frac{\partial f}{\partial s} \hat{s} + \frac{1}{s} \frac{\partial f}{\partial \phi} \hat{\phi} + \frac{\partial f}{\partial z} \hat{z} \quad \nabla \cdot \vec{A} = \frac{1}{s} \frac{\partial(s A_s)}{\partial s} + \frac{1}{s} \frac{\partial A_\phi}{\partial \phi} + \frac{\partial A_z}{\partial z}$$

$$\nabla \times \vec{A} = \left(\frac{1}{s} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right) \hat{s} + \left(\frac{\partial A_s}{\partial z} - \frac{\partial A_z}{\partial s} \right) \hat{\phi} + \frac{1}{s} \left(\frac{\partial(s A_\phi)}{\partial s} - \frac{\partial A_s}{\partial \phi} \right) \hat{z} \quad \nabla^2 f = \frac{1}{s} \frac{\partial}{\partial s} \left(s \frac{\partial f}{\partial s} \right) + \frac{1}{s^2} \frac{\partial^2 f}{\partial \phi^2} + \frac{\partial^2 f}{\partial z^2}$$

Tensor Math: $(\vec{a} \cdot \vec{T})_j = \sum_i a_i T_{ij} \quad (\vec{T} \cdot \vec{a})_j = \sum_i T_{ji} a_i$

Lorentz Force: $\vec{F} = Q(\vec{E} + \vec{v} \times \vec{B}), \quad \text{On Wire: } \vec{F}_{mag} = \int I(\vec{dl} \times \vec{B})$

Maxwell's Equations:

$$\begin{aligned} \nabla \times \vec{E} &= -\frac{\partial \vec{B}}{\partial t} & \oint \vec{E} \cdot \vec{dl} &= -\frac{d}{dt} \int \vec{B} \cdot \vec{da} \\ \nabla \cdot \vec{E} &= \rho/\epsilon_0 & \oint \vec{E} \cdot \vec{da} &= Q_{enc}/\epsilon_0 \\ \nabla \times \vec{B} &= \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} & \oint \vec{B} \cdot \vec{dl} &= \mu_0 I_{enc} + \mu_0 \epsilon_0 \frac{d}{dt} \int \vec{E} \cdot \vec{da} \\ \nabla \cdot \vec{B} &= 0 & \oint \vec{B} \cdot \vec{da} &= 0 \end{aligned}$$

Fields in Matter: $\vec{P} = \vec{p}/\text{volume}$ $\vec{D} = \epsilon_0 \vec{E} + \vec{P}$ $\sigma_b = \vec{P} \cdot \hat{n}$ $\rho_b = -\nabla \cdot \vec{P}$ $\vec{J}_p = \frac{\partial \vec{P}}{\partial t}$
 $\vec{M} = \vec{m}/\text{volume}$ $\vec{H} = \frac{1}{\mu_0} \vec{B} - \vec{M}$ $\vec{K}_b = \vec{M} \times \hat{n}$ $\vec{J}_b = \nabla \times \vec{M}$
 $\nabla \cdot \vec{D} = \rho_f$ $\oint \vec{D} \cdot d\vec{a} = Q_{f_enc}$
 $\nabla \times \vec{H} = \vec{J}_f + \frac{\partial \vec{D}}{\partial t}$ $\oint \vec{H} \cdot d\vec{l} = I_{f_enc} + \frac{d}{dt} \int \vec{D} \cdot d\vec{a}$

Linear Materials: $\vec{P} = \epsilon_0 \chi_e \vec{E}$ $\vec{D} = \epsilon \vec{E} = (1 + \chi_e) \epsilon_0 \vec{E} = \epsilon_r \epsilon_0 \vec{E}$
 $\vec{M} = \chi_m \vec{H}$ $\vec{B} = \mu \vec{H} = (1 + \chi_m) \mu_0 \vec{H}$

Boundary Conditions: $\Delta D_{\perp} = \sigma_f$ $\Delta \vec{E}_{\parallel} = 0$ $\Delta \vec{D}_{\parallel} = \Delta \vec{P}_{\parallel}$
 $\Delta \vec{H}_{\parallel} = \vec{K}_f \times \hat{n}$ $\Delta B_{\perp} = 0$ $\Delta H_{\perp} = -\Delta M_{\perp}$

Ohm's Law and EMF: $\vec{J} = \sigma \vec{E}$ $\mathcal{E} = \oint (\vec{F}/q) \cdot d\vec{l}$ $\mathcal{E}_{\text{motional}} = -\frac{d\Phi_B}{dt}$

Inductance: $M = \frac{\Phi_{B2}}{I_1} = \frac{\Phi_{B1}}{I_2}$ $L = \frac{\Phi_{B1}}{I_1}$ $\mathcal{E}_{\text{induced}} = -L \frac{dI}{dt}$ $\frac{dW}{dt} = \mathcal{E}I$

Continuity of Charge/Current: $\frac{\partial \rho}{\partial t} = -\nabla \cdot \vec{J}$ $\frac{\partial \rho_b}{\partial t} = -\nabla \cdot \vec{J}_p$

Energy & Momentum: $\vec{S} = \frac{1}{\mu_0} (\vec{E} \times \vec{B})$ $u_{EM} = \frac{1}{2} (\epsilon_0 E^2 + \frac{B^2}{\mu_0})$ $U_{EM} = \int u_{EM} d\tau$
 $T_{ij} = \epsilon_0 (E_i E_j - \frac{1}{2} \delta_{ij} E^2) + \frac{1}{\mu_0} (B_i B_j - \frac{1}{2} \delta_{ij} B^2)$ $\vec{g} = \epsilon_0 (\vec{E} \times \vec{B}) = \mu_0 \epsilon_0 \vec{S}$ $\vec{p}_{EM} = \int \vec{g} d\tau$
 $\frac{dW}{dt} = -\oint \vec{S} \cdot d\vec{a} - \frac{dU_{EM}}{dt}$ $\frac{\partial u_{EM}}{\partial t} = -\nabla \cdot \vec{S}$ if $\frac{dW}{dt} = 0$
 $\vec{F} = \frac{d\vec{p}_{mech}}{dt} = \oint \vec{T} \cdot d\vec{a} - \frac{d\vec{p}_{EM}}{dt}$ $\vec{f} = \nabla \cdot \vec{T} - \frac{\partial \vec{g}}{\partial t}$ $\frac{\partial \vec{g}}{\partial t} = \nabla \cdot \vec{T}$ if $\vec{f} = 0$

EM Waves:

Complex: $\vec{E}(\vec{r}, t) = \vec{E}_0 \exp(i(\vec{k} \cdot \vec{r} - \omega t)) \hat{n}$ $\vec{B}(\vec{r}, t) = \frac{k}{\omega} \vec{E}_0 \exp(i(\vec{k} \cdot \vec{r} - \omega t)) (\hat{k} \times \hat{n})$
Real: $\vec{E}(\vec{r}, t) = E_0 \cos(\vec{k} \cdot \vec{r} - \omega t + \delta) \hat{n}$ $\vec{B}(\vec{r}, t) = \frac{k}{\omega} E_0 \cos(\vec{k} \cdot \vec{r} - \omega t + \delta) (\hat{k} \times \hat{n})$
 $\frac{\omega}{k} = c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$ $\langle u \rangle = \frac{1}{2} \epsilon_0 E_0^2$ $\langle \vec{S} \rangle = c \langle u \rangle \hat{k} = I \hat{k} = \frac{1}{2} c \epsilon_0 E_0^2 \hat{k}$ $\langle \vec{g} \rangle = \frac{\langle \vec{S} \rangle}{c^2} = \frac{1}{2c} \epsilon_0 E_0^2 \hat{k}$
 $P = \frac{I}{c} = \frac{\langle S \rangle}{c}$